

# Adaptive Methods

High Resolution Recovery of Piecewise Smooth  
Data from its Spectral Information

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# Outline

- Review of Fourier approximations for smooth(periodic) functions.
- Piecewise smooth functions - practical computational data.
- Adaptive Mollifiers for the high order resolution of Gibbs' Phenomena.
  - error analysis  $\rightarrow$  exponential accuracy for piecewise analytic, numerics

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- Piecewise smooth functions - practical computational data.
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  - error analysis  $\rightarrow$  exponential accuracy for piecewise analytic, numerics
- Adaptive Filters
  - overview of error analysis, numerics

# Global(Periodic) Regularity and High Resolution

## Spectral Convergence Rate, $C^s$

$$|S_N f(x) - f(x)| \leq Const \|f\|_{C^s} \cdot \frac{1}{N^{s-1}} \quad \forall s$$

$$\odot \|f\|_{C^s} := \max_{[-\pi, \pi]} |f^{(s)}|$$

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## Exponential Convergence Rate, Analytic

$$|S_N f(x) - f(x)| \leq \text{Const}_\eta \cdot N e^{-N\eta} \quad \Leftrightarrow \quad \|f\|_{C^s} \leq \text{Const} \cdot \frac{s!}{\eta^s}$$

Behavior of  $f(\cdot)$  off the real axis determines  $\eta$ .

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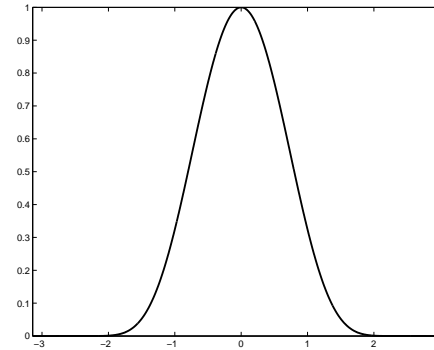
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Behavior of  $f(\cdot)$  off the real axis determines  $\eta$ .

- Convergence rate as fast as *Global* smoothness permits.
- What about  $f \in C^\infty$  non-analytic? Gevrey regularity.

## What about Spectral Convergence for $C^\infty$ ?

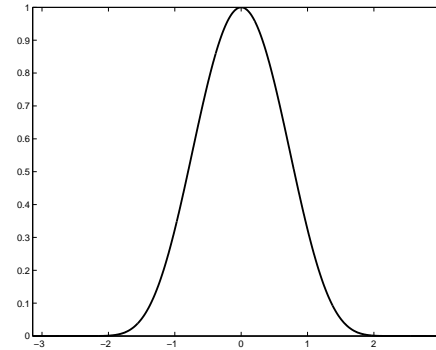
$$\rho(x) = \begin{cases} \exp\left(\frac{(\pi x)^2}{x^2 - \pi^2}\right) & |x| < \pi \\ 0 & |x| \geq \pi. \end{cases}$$



Between exponential(Analytic) and spectral( $C^s$ ) is Gevrey Regularity,

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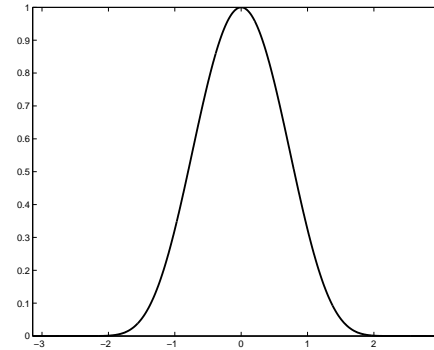
$\rho(\cdot)$  is *Gevrey regular* of order 2,  $\rho^{(s)} \sim (s!)^2$ ,

$$|S_N \rho - \rho| \leq \text{Const}_{\eta_\rho} \cdot N e^{-2\sqrt{\eta_\rho N}}.$$



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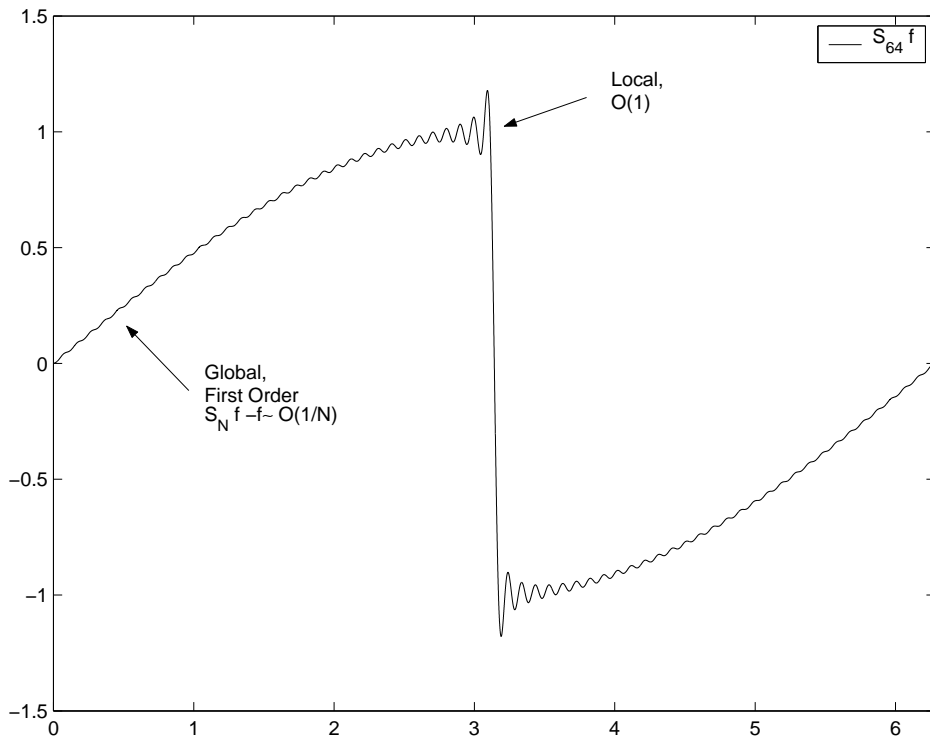
$$|S_N \rho - \rho| \leq \text{Const}_{\eta_\rho} \cdot N e^{-2\sqrt{\eta_\rho N}}.$$

*Fractional power* exponential convergence.

$$|S_N \psi - \psi| \leq \text{Const}_\eta \cdot N^{\alpha/2} e^{-\alpha(\eta N)^{1/\alpha}} \quad \Leftrightarrow \quad \|\psi\|_{G^\alpha} \leq \text{Const} \cdot \frac{(s!)^\alpha}{\eta^s}$$

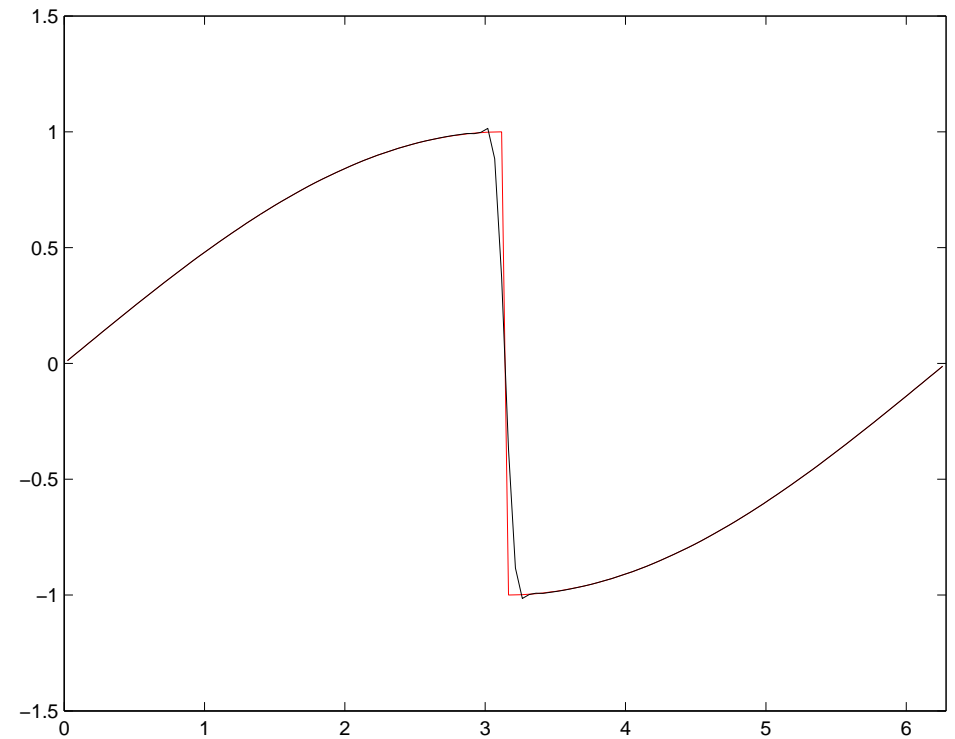
# Gibbs' Phenomena and Filtered Reconstruction

$$f(x) = \begin{cases} \sin(x/2) & x \in [0, \pi) \\ -\sin(x/2) & x \in [\pi, 2\pi) \end{cases}$$



$S_{64}f(x)$

$\Rightarrow$



$S_{64}^\sigma f(x)$

- High order reconstruction with Gibbs' Phenomena removed.

## Methods for discontinuous data

### **Local Smoothness, fixed polynomial order**

- Splines
  - Wavelets
  - WENO
- $$\left. \begin{array}{l} \bullet \text{ Splines} \\ \bullet \text{ Wavelets} \\ \bullet \text{ WENO} \end{array} \right\} P_N f - f \sim O\left(\frac{1}{N^r}\right) \quad \text{fixed } r$$

### **Semi-Global Smoothness, spectral accuracy**

- Gegenbauer
  - Filters/Mollifiers
- $$\left. \begin{array}{l} \bullet \text{ Gegenbauer} \\ \bullet \text{ Filters/Mollifiers} \end{array} \right\} P_N f - f \sim C_s \frac{1}{N^s}, \quad \forall s$$

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Filtering and Mollification are essentially interchangeable,

$$\sum_{|k| \leq N} \sigma\left(\frac{|k|}{N}\right) \hat{f}_k e^{ikx} \quad \Leftrightarrow \quad \phi * S_N f(x)$$

Dual Space

Physical Space

- ⊙ When to filter in dual space or mollify in physical space?
- ⊙ Computationally more efficient to stay is the space of given data.

## Canonical Polynomial Order Mollifiers

- *One-parameter* compactly supported,  $(-\pi, \pi)$ , functions.

$$\psi_\theta(x) := \frac{1}{\theta} \psi\left(\frac{x}{\theta}\right), \quad -\pi\theta \leq x \leq \pi\theta$$

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- Convergence order as fixed number of exactly vanishing moments

$$\int_{-d}^d x^j \psi_\theta(x) dx = \delta_{j,0} \quad j = 0, 1, 2, \dots, r-1.$$

- Local  $|f - f * \psi_\theta| \leq \frac{\theta^r}{\pi^r (r+1)!} \|f^{(r)}\|_{L^\infty(x-\pi\theta, x+\pi\theta)}$

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- Local  $|f - f * \psi_\theta| \leq \frac{\theta^r}{\pi^r (r+1)!} \|f^{(r)}\|_{L^\infty(x-\pi\theta, x+\pi\theta)}$
- Error decreases at *fixed polynomial order*  $(\theta^r)$ ,  $\theta \downarrow 0$ .
- Recover from  $S_N f(\cdot)$  requires similar order *regularity*,  $\psi \in C^r$ .
- Inherent small scale introduced by projection(sampling),  $h \sim 1/N$ .

# Adaptive Mollifier of Tadmor(Gottlieb) & Tanner

The *two parameter* mollifier is given by:

$$\psi_{p,\theta}(x) := \frac{1}{\theta} \rho\left(\frac{x}{\theta}\right) D_p\left(\frac{x}{\theta}\right)$$

⊙  $\rho(\cdot)$ , our  $G_0^2$  localizer 
$$\rho(x) = \begin{cases} \exp\left(\frac{(\pi x)^2}{x^2 - \pi^2}\right) & |x| < \pi \\ 0 & |x| \geq \pi. \end{cases}$$

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- Cancellation:  $\psi_{p,\theta}$  possesses  *$p$  near vanishing moments*.

$$\int_{-\pi\theta}^{\pi\theta} x^j \psi_{p,\theta}(y) dy = \delta_{j0} + C_j \cdot p^{-(j-1)}, \quad \forall j \leq p$$

- Unlike traditional mollifiers, dilation parameter as large as allowable

## Error Analysis of Adaptive Mollifiers

*Pointvalue* recovery from a spectral projection,  $S_N f(\cdot)$ ,  
or equidistant sampling  $I_N f(\cdot)$ .

Error composed of two terms:

$$\begin{aligned}\text{Error} &:= \psi_{p,\theta} * S_N f(x) - f(x) \\ &\equiv (f * \psi_{p,\theta} - f) + (S_N f - f) * (\psi_{p,\theta} - S_N \psi_{p,\theta})\end{aligned}$$

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- Truncation  $:= (S_N f - f) * (\psi_{p,\theta} - S_N \psi_{p,\theta})$ 
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## Error Analysis:

- The optimal number of near vanishing moments,  $p$ .
- Justify selection of dilation parameter,  $\theta\pi := d(x)$ .

Revisited: Error=Regularization+Truncation

## Error Analysis I, Regularization Error

- $f(\cdot)$  analytic in  $(x - d(x), x + d(x))$  where  $d(x)$  distance to discontinuity, and  $\rho \in G^2$ , therefore  $g_x(y) := f(x + y)\rho_{d(x)}(y) - f(x)$  is Gevrey order 2.

$$\begin{aligned} |\text{Regularization}| &:= |f * \psi_{p,\theta} - f| \\ &= |S_p g_x(y) - g_x(y)|_{y=0} \\ &\leq C_\rho \cdot p \cdot e^{-2\sqrt{p \cdot \eta_\rho}} \end{aligned}$$

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- Hidden dependence on dilation,  $\theta$ , in  $\eta_\rho$ .
- Dilation parameter,  $\theta$ , as large as possible such that  $f(\cdot)$  analytic in  $(x - \theta\pi, x + \theta\pi) \Rightarrow \theta\pi := d(x)$ .
- Non-Linear Adaptive Mollification,  $\theta(x) := d(x)/\pi$ .
- ⊙ Symmetric reconstructions must sacrifice accuracy as approaching edges.

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## Error Analysis II, Truncation error

- Smoothness reflected as dual space localization,  $(\psi - S_N\psi)$ , truncation.
- Dirichlet Kernel analytic and  $\rho \in G^2 \Rightarrow \psi_{p,\theta(x)}$  Gevrey order 2,

$$\|\psi_{p,\theta(x)}\|_{C^s} \leq C_\rho \cdot s \cdot \left( \frac{s^2}{e^{2\eta\theta(x)}} \right)^s e^{p\eta/s} \quad s = 1, 2, \dots$$

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$\theta(x)$  in denominator dictates  $\Rightarrow \theta(x)$  as large as possible.



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Remaining:

- Equilibration of Regularization and Truncation Error.
- The optimal number of near vanishing moments,  $p$ .

## Error Analysis III, Determination of parameter, $p$

- Truncation minimized over  $s$  when:

$$\log \left( \frac{s_{min}^2 \pi}{\eta N d(x)} \right) = \frac{p \eta_c}{s_{min}^2} \Rightarrow s_{min} \sim \sqrt{\eta \cdot N d(x)}$$

Incorporating this relationship for  $s_{min}$  yields

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- Adaptivity: The optimal choice for the number of near vanishing moments,  $p$ , is given as a function of the distance to the nearest discontinuity!

$$p_{min} := k \cdot Nd(x)$$

$k$  selected to balance Regularization and Truncation errors,  $k = 0.5596$ .

## Near discontinuities, Normalization

- $O(1/N)$  neighborhood of discontinuity,  $p \sim Nd(x) \approx 1$ .
- *Error for vanishing moments is substantial.*

$$\int_{-d}^d y^j \psi_{p,d}(y) dy = S_p * (y^j \rho(y)) \Big|_{x=0} \sim \delta_{j0} + \text{Const}_j \cdot p^{-(j-1)}$$

- Visible error near discontinuities (blurring).

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- Visible error near discontinuities (blurring).
- To maintain at least first order accuracy, normalize to unit mass

$$\psi_{N,d(x)}^{norm} := \frac{\psi_{Nd(x)}}{\int_{-d}^d \psi_{Nd(x)} dx}.$$

- Can possess any fixed number of exactly vanishing moments.
- Polynomial convergence near edges and exponential accuracy away.

## *There are no free parameters*

- Exponential Accuracy away from discontinuity,  $d(x) > O(1/N)$ .

$$|\psi_{Nd(x)} * S_N f(x) - f(x)| \leq C_\rho \cdot Nd(x) e^{-0.845 \sqrt{\eta \cdot Nd(x)}}.$$

- Explicit reconstruction depending only on the projection order,  $N$ , and the discontinuity locations,  $d(x)$ .
- Computationally robust due to rapidly decaying localizer,  $\rho(\cdot)$ .
- Optimal number of near vanishing moments given adaptively by

$$p_{min}(N, x) := k \cdot Nd(x)$$

- Polynomial order accuracy in  $O(1/N)$  neighborhood of discontinuities

## Pseudospectral(Equidistant) Recovery

$$\hat{f}_k := \int_{-\pi}^{\pi} f(x) e^{ikx} dx \quad \Rightarrow \quad \tilde{f}_k := \frac{\pi}{N} \sum_{\nu=-N}^{N-1} f(y_{\nu}) e^{iky_{\nu}} \quad y_{\nu} := \frac{\pi}{N} \nu$$

Exponential accuracy the same order as spectral projection:

$$\left| \frac{\pi}{N} \sum_{\nu=-N}^{N-1} \psi_{Nd(x)}(x - y_{\nu}) f(y_{\nu}) - f(x) \right| \leq \text{Const}_c \cdot (Nd(x))^2 e^{-\sqrt{\eta \cdot Nd(x)}}$$

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- The pseudospectral coefficients are not needed; **only samples  $f(y_{\nu})$** .
- Robust exponentially accurate method to recover intermediate function values given an equidistant sampling of a piecewise smooth function.
- **Accuracy proportional to number of cells to nearest discontinuity.**
- Optimal order symmetric reconstruction, contrast with CWENO.

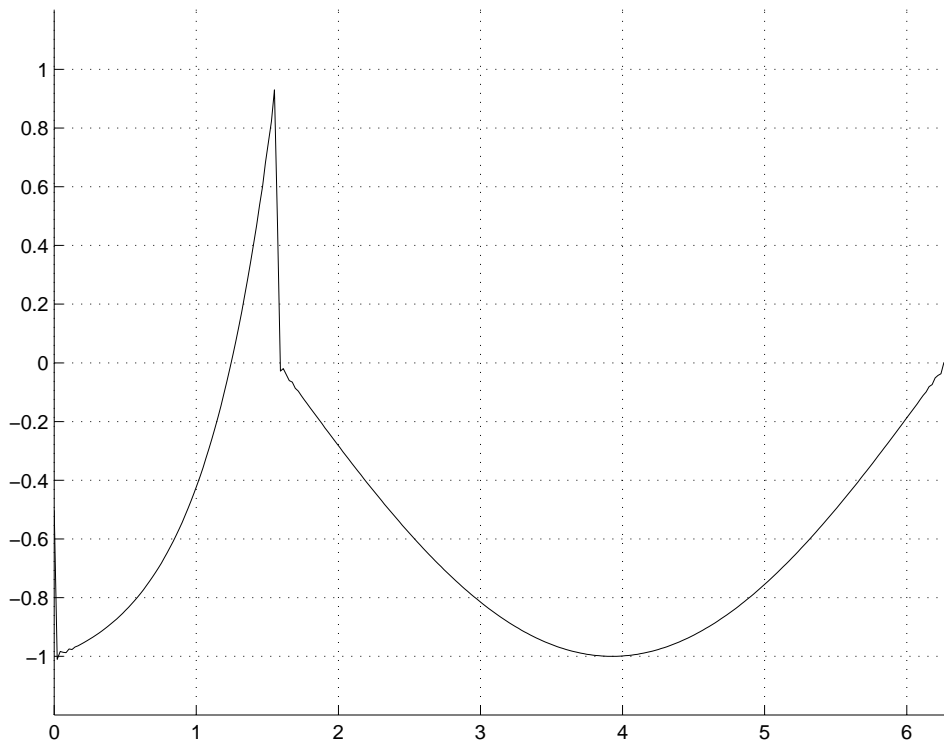
However, this is not Interpolation!



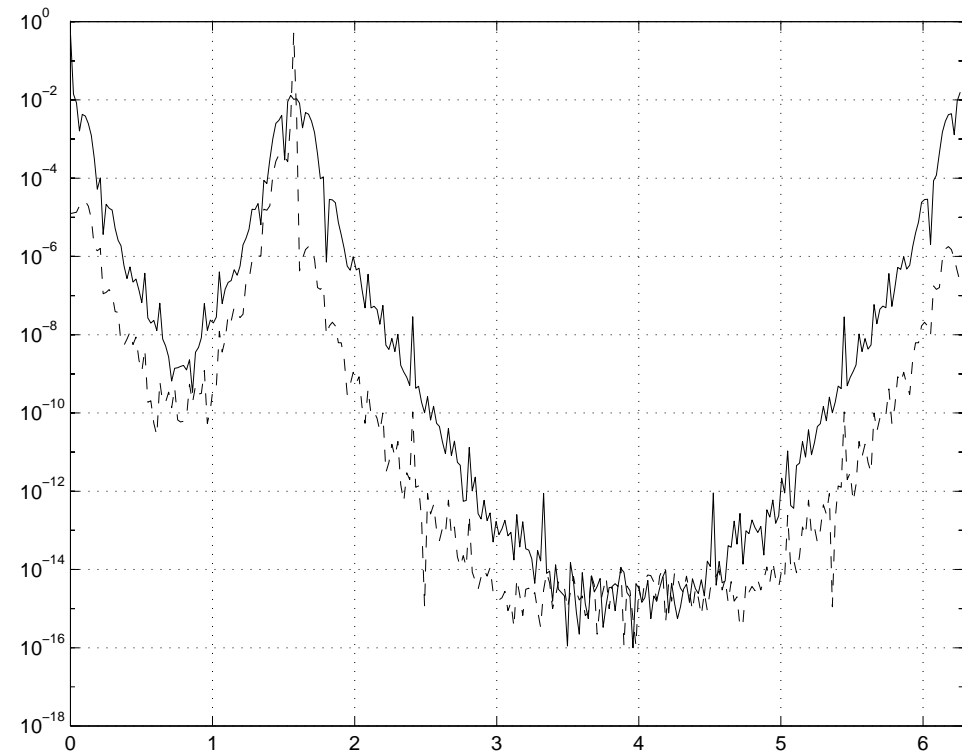
# Reconstruction from Spectral Projection

$$f_2(x) = \begin{cases} (2e^{2x} - 1 - e^\pi)/(e^\pi - 1) & x \in [0, \pi/2) \\ -\sin(2x/3 - \pi/3) & x \in [\pi/2, 2\pi) \end{cases}$$

Reconstruction  $\psi * S_{128}f(\cdot)$



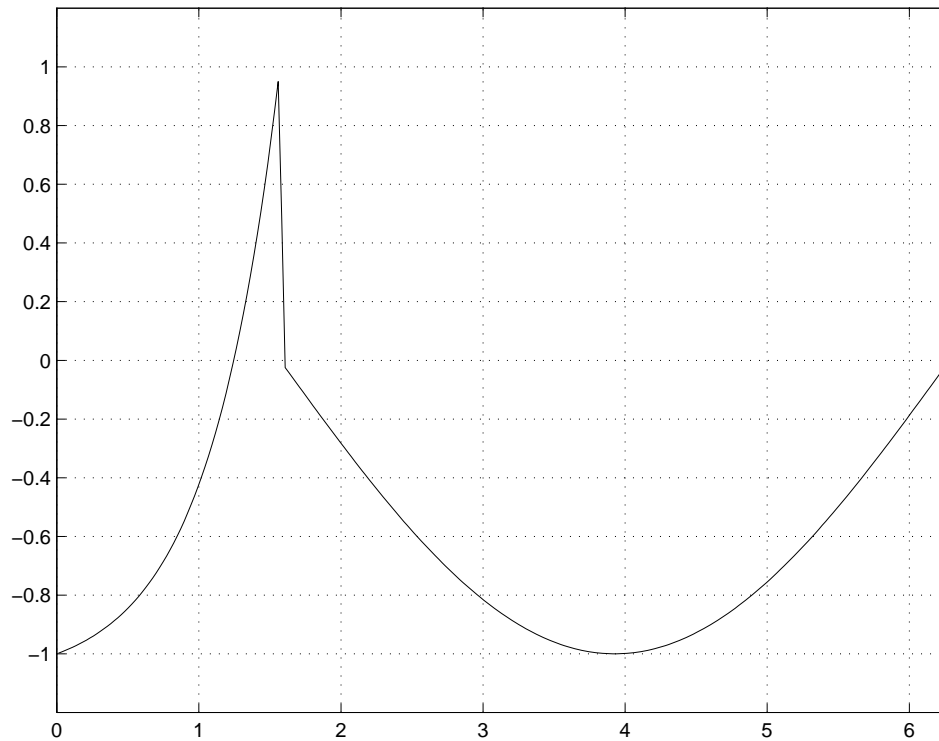
Regularization & Truncation errors



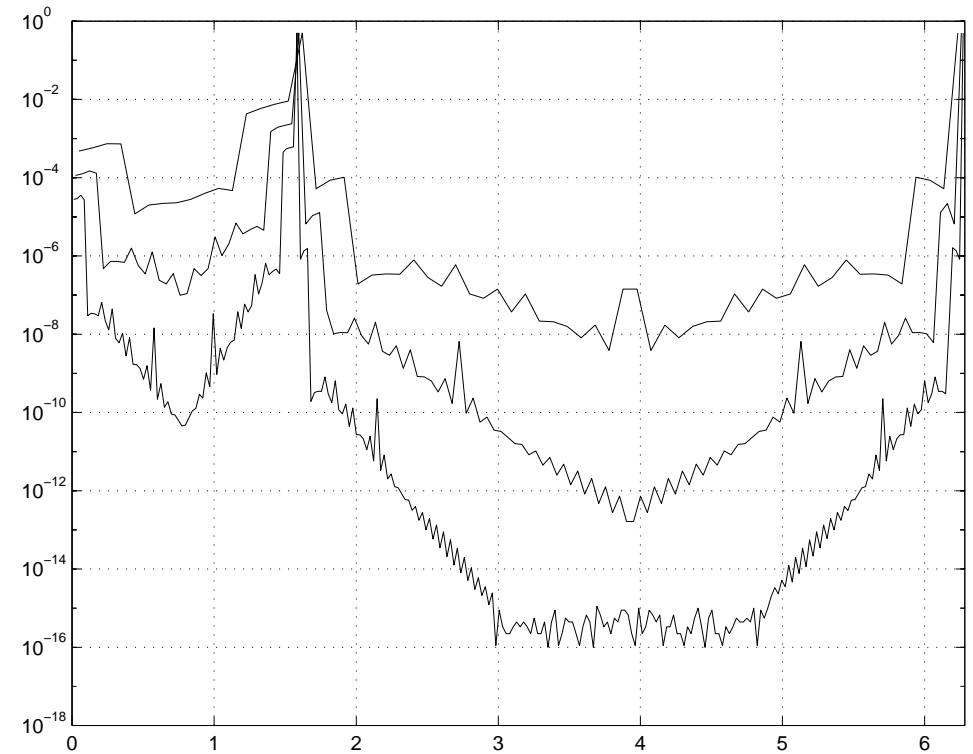
- Balanced decay rate of Regularization and Truncation errors
- Different regularity constants, steep gradient at  $\frac{\pi}{2}^-$
- Accuracy sacrificed near discontinuities

# Reconstruction from equidistant samples

Reconstruction,  $\psi_{Nd(x)} * I_{128}f(\cdot)$



Log of error,  $N = 32, 64, 128$

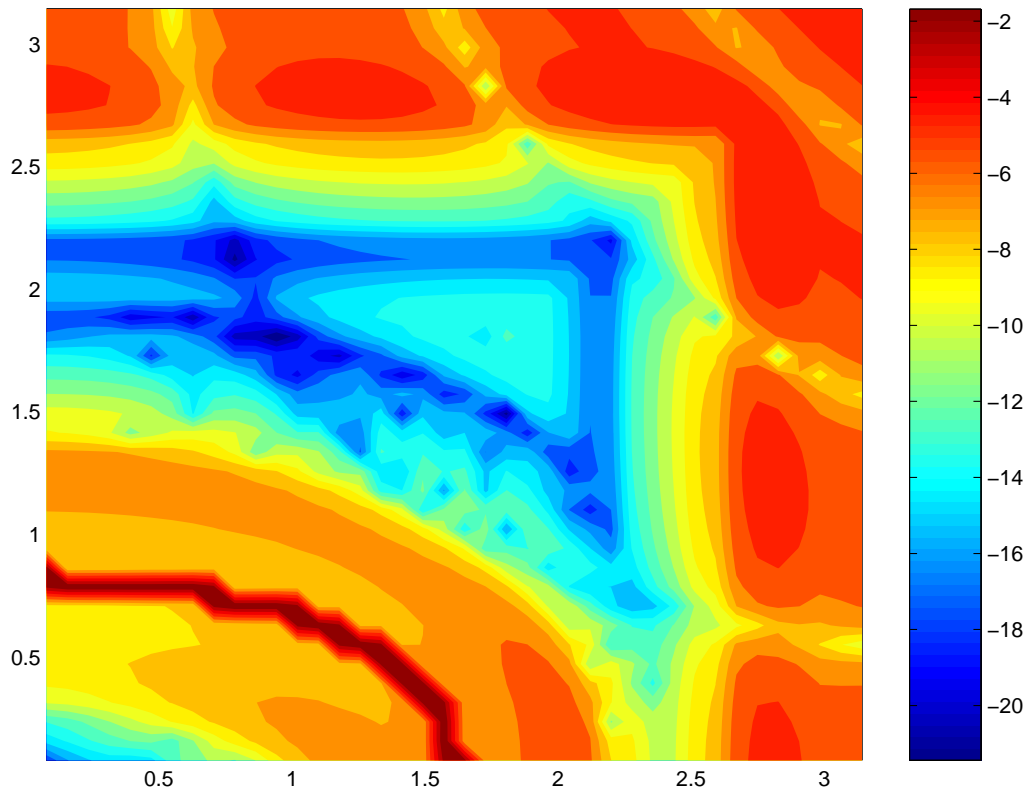


- Exponential convergence away from discontinuity
- Polynomial order accuracy near discontinuity,  $d(x) = O(1/N)$
- Exact physical space localization, sharp resolution of discontinuities

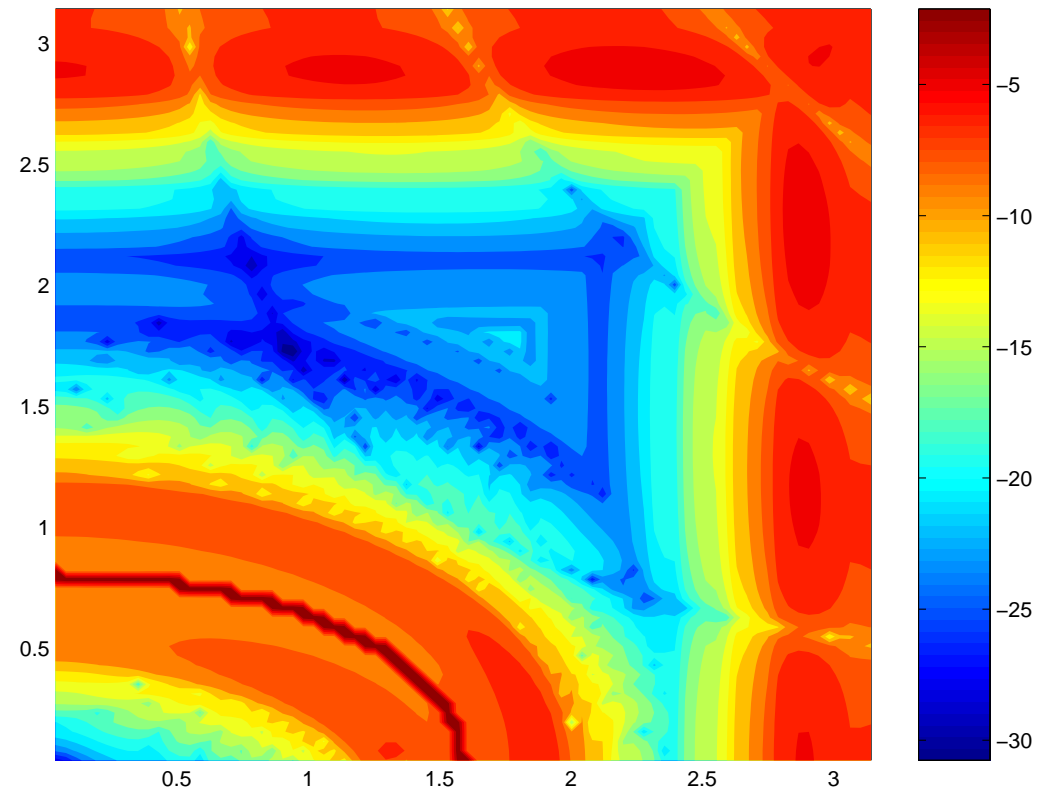
## 2D Pseudospectral Example

$$f(x, y) = \begin{cases} \cos(xy) + 1 & 4x^2 + 16y^2 \leq \pi^2 \\ \cos(xy) & \text{else} \end{cases}$$

Error with  $N = 40$



$N = 80$



- Also treating boundaries as discontinuities,  $x = \pm\pi, y = \pm\pi$ .

# Summary of Adaptive Mollifiers

- Recovers pointwise function values of piecewise smooth functions given either its spectral projection, or equidistant sampling.
- No parameters determined by the user, a “Black Box” method.
- *Computationally robust* and well suited for fast parallel computations.
- *Exponentially accurate* away from the discontinuity and fixed polynomial order convergence rate in the  $O(1/N)$  neighborhood of edges.

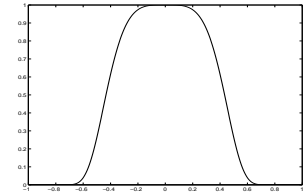
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- Reconstruction errors a combination of
  - near vanishing moments, regularization
  - physical space localization
  - dual space localization, truncation $\left. \vphantom{\begin{matrix} - \\ - \\ - \end{matrix}} \right\} \Rightarrow \text{Adaptive Filters}$

## Filters - Classical Polynomial Order

- Piecewise smooth functions, slowly decaying coefficients,  $\hat{f}_k \leq O(k^{-1})$
- Filters increase convergence order by increasing coefficient decay rate

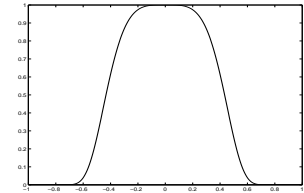
Filter properties  $\Rightarrow \begin{cases} - \text{smoothness, } \sigma(\eta) \in C_0^q[-1, 1] \\ - \text{accuracy, } \sigma^{(j)}(0) = \delta_{j0}, \quad j \leq q - 1 \end{cases}$



## Filters - Classical Polynomial Order

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- Acts on function and its projection the same, dual space localization

$$f^\sigma(x) \equiv S_N f^\sigma(x) := \sum_{|k| \leq N} \sigma\left(\frac{|k|}{N}\right) \hat{f}_k e^{ikx}$$

- Error analysis through associated mollifier, acting in physical space

$$S_N f^\sigma(x) := f * \Phi(x) = \int_{-\pi}^{\pi} \Phi(y) f(x - y) dy \quad \Phi(x) := \sum_{|k| \leq N} \sigma\left(\frac{k}{N}\right) e^{ikx}$$

## Error Analysis - Sketch

- Accuracy condition implies a number of **near vanishing moments**

$$\sigma^{(j)}(0) \equiv \delta_{j,0} \quad \Rightarrow \quad \int_{-d}^d y^j \Phi(y) dy \sim \delta_{j,0} \quad j = 0, 1, 2, \dots, q-1.$$

- However, increased filter order,  $q$ , decreases localization
- Error composed of competing localization and accuracy errors,

$$|f(x) - f * \Phi(x)| \leq \left| \int_{d(x) < |y| \leq \pi} \Phi(y) g_x(y) dy \right| + \left| \int_{|y| \leq d(x)} \Phi(y) g_x(y) dy \right|$$

where,  $g_x(y) := f(x) - f(x - y)$ .



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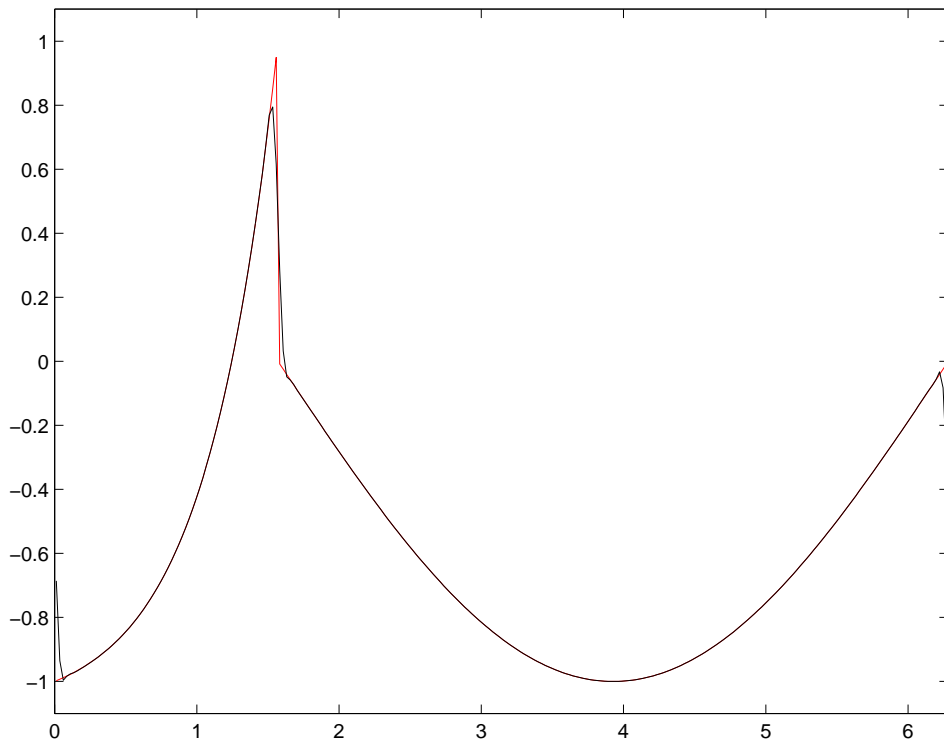
- Fixed order filters **fail to balance accuracy and localization errors**
- Optimal filter order is spatially adaptive, balancing competing errors

$$q_{min} := (k \cdot Nd(x))^{1/\alpha} \quad \sigma \in G_0^\alpha[-1, 1]$$

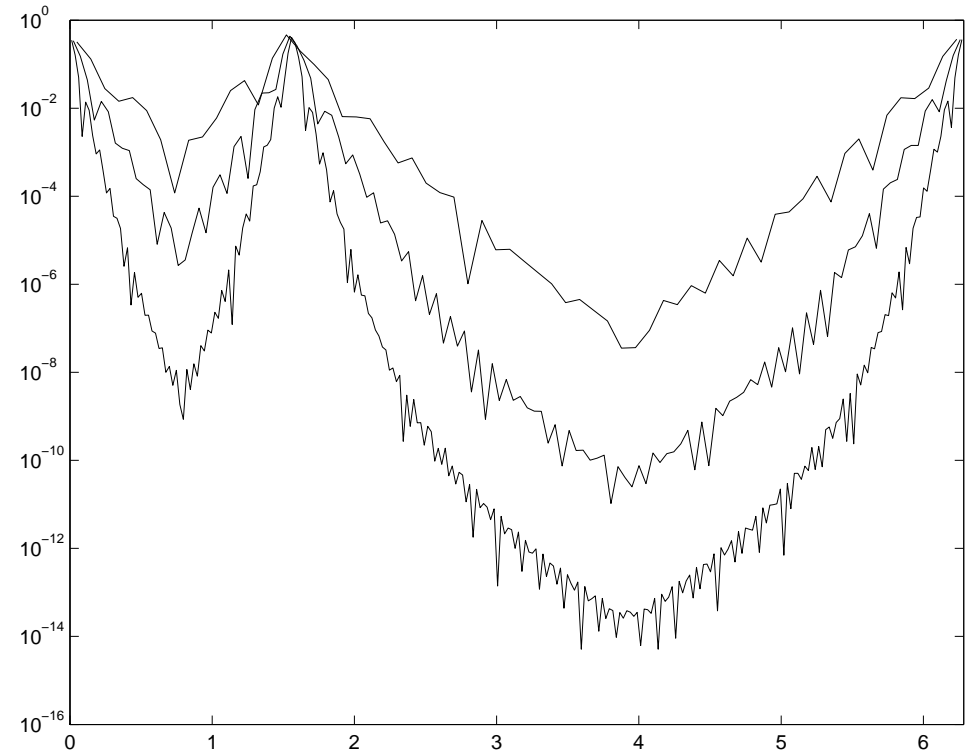
## Reconstruction with Adaptive Filter

$$f_2(x) = \begin{cases} (2e^{2x} - 1 - e^\pi)/(e^\pi - 1) & x \in [0, \pi/2) \\ -\sin(2x/3 - \pi/3) & x \in [\pi/2, 2\pi) \end{cases}$$

Reconstruction,  $S_{128}f^\sigma(\cdot)$



$|f(x) - S_N f^\sigma(x)|, N = 32, 64, 128$



- Similar accuracy to Adaptive Mollifier
- Computationally fast when given spectral projection

# Adaptive Mollifiers & Filters

A Powerful tool for manipulating a function's spectral projection or equidistant sampling.

Thank you

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